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Introduction: MH370

On March 8, 2014 Malaysia Airlines Flight MH370 disappeared less than an hour after take-off on a flight from Kuala Lumpur to Beijing. The Boeing 777-200ER carried 12 crew members and 227 passengers.

"It is therefore with deep sadness and regret that I must inform you that ... Flight MH370 ended in the Southern Indian Ocean."

Malaysia Prime Minister
 Perdana Menteri





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Introduction: An Interdisciplinary Perspective

Research on this air incident requires interdisciplinary perspective. Computational mathematics and mechanics can help us:

- understand the physical nature of an aircraft emergency water landing
- model and compute this problem
- use this knowledge to help safe civil aviation and other aerospace related undertakings

- 3 pm, Tue, Nov 17
- 11 am, Wed, Nov 18
- 3 pm, Wed, Nov 18



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Challenges for Classical Methods

Sub-models and corrections are needed for various complicating factors

- trapped air cavitation
- water compressibility and acoustic effects
- complex, real-world geometries





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Approach and Objective

Flight MH370:

• If fight MH370 did not have a mid-air explosion, then all available signs indicate that it crashed somewhere in the Indian Ocean. This is an aircraft water-entry problem.

Approach:

 Instead of the classical methods introduced above, we utilize Computation Fluid Dynamics (CFD) that can resolve local details and take factors like trapped air, water compressibility, and the real-world geometry (Boeing 777) into account.

Objective:

• Numerically simulate and analyze several hypothetical scenarios.

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OpenFOAM: Software Platform

OpenFOAM (Open Source Field Operation and Manipulation) is an free and open-source C++ toolbox for the development of customized numerical solvers, and pre-/post-processing utilities for the solution of continuum mechanics problems, including CFD.

There are three steps to run OpenFOAM

- generate polyhedral mesh
- execute a numerical solver for the given differential equation
- display and analyze the results





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Aircraft Water Entry





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Governing Equations I

• (Conservation of phase mass)

 $\frac{\partial(\rho_i\alpha_i)}{\partial t} + \nabla \cdot (\rho_i\alpha_i \boldsymbol{u}) = 0.$

 α_i = volume fraction of phase *i*, and $\alpha_1 + \alpha_2 = 1$.

• (Conservation of momentum)

$$\frac{\partial(\rho \boldsymbol{u})}{\partial t} + \nabla \cdot (\rho \boldsymbol{u} \boldsymbol{u}) = -\nabla_p + \nabla \cdot T + \rho g + f_{surf},$$

$$T = \mu \left(\nabla \boldsymbol{u} + \nabla \boldsymbol{u}^T\right) - \frac{2}{3}\mu \left(\nabla \cdot \boldsymbol{u}\right) I,$$

$$\rho = \text{mixture density} = \rho_1 \alpha_1 + \rho_2 \alpha_2,$$

$$\mu = \text{mixture viscosity.}$$

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Governing Equations II

• (Continuum surface force) $f_{surf} = {}_{\gamma K} \nabla \alpha_1$,

 $K = \text{interface curvature} = -\nabla \cdot \left(\frac{\nabla \alpha_1}{|\nabla \alpha_1|}\right),$ $\gamma = \text{surface tension.}$

• (Material equation of state) $\rho_1 = \text{water density} = \rho_0 + \varphi_1 \rho,$ $\rho_2 = \text{air density} = \varphi_2 \rho.$ • (Six degrees of freedom of motion) $\sigma = -\rho I + T$,

F(t) =force on object $= \int_{\partial \Omega(t)} \boldsymbol{\sigma} \hat{\boldsymbol{n}} \, dS$,

 $\tau(t) = \text{torque on object} = \int_{\partial \Omega(t)} \mathbf{r} \times \boldsymbol{\sigma} \hat{\mathbf{n}} \, dS.$

- $\Rightarrow \text{Resulting velocity on object skin } V(x, t)$ for $x \in \partial \Omega(t)$
- (Moving boundary condition on object skin) $\mathbf{u}|_{\partial\Omega(t)} = V(x, t)$



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Scenario with 30°-Diving ($\theta = -30^\circ$, $\beta = 30^\circ$)







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Scenario with Nose-Diving ($\theta = -90^\circ$, $\beta = 93^\circ$)



Bending Moment



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